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MODEL: Robot-TP-84M

Teach Pendant with 4-wire Resistive Type Touchscreen, Deadman Switch, Emergency Button, IP 64 Protection and RoHS

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User Manual



Rev. 1.00 - June 23, 2016

Revision

Date	Version	Changes
June 23, 2016	1.00	Initial release



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Manual Conventions



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WARNING

Warnings appear where overlooked details may cause damage to the equipment or result in personal injury. Warnings should be taken seriously.



CAUTION

Cautionary messages should be heeded to help reduce the chance of losing data or damaging the product.



NOTE

These messages inform the reader of essential but non-critical information. These messages should be read carefully as any directions or instructions contained therein can help avoid making mistakes.



HOT SURFACE

This symbol indicates a hot surface that should not be touched without taking care.

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Introduction





1.1 Overview



Figure 1-1: Robot-TP-84M Teach Pendant

The Robot-TP-84M is a teach pendant with 8.4" 4-wire resistive touchscreen. The Robot-TP-84M is designed for easy and simplified integration into robot arm applications.

1.2 Model Variation

The Robot-TP-84M series has two models. The model variation is listed below:

Model	Brightness	Cable Connection
Robot-TP-84M/K-R11	350 cd/m ²	One 37-pin military connector
Robot-TP-84M/K-ML-R11	350 cd/m ²	Multiple cables and connectors

Table 1-1: Model Variation

1.3 Features

The Robot-TP-84M features are listed below:

- 350 cd/m² high brightness LCD with LED backlight
- 4-wire resistive type touchscreen
- 6-meter long all-in-one cable allows easy installation
- Completely dust and splash proof (IP 64) design, IEC60529 compliant
- One meter drop resistance, MIL-810G 516.60IV compliant
- 0°C~50°C extended operating temperature

 Equipped with an emergency stop and a 3-position deadman switch to provide safe operation

1.4 Front Panel

The front side of the Robot-TP-84M is a flat bezel panel TFT LCD screen surrounded by a PC/ABS plastic frame.





1.5 Rear Panel

The rear panel provides access to the deadman switch. Refer to Figure 1-5.









1.6 Dimensions

The Robot-TP-84M dimensions are shown below.



Figure 1-4: Robot-TP-84M Dimensions (mm)

1.7 System Specifications

The technical specifications for the Robot-TP-84M systems are listed in Table 1-4.

Specification		Robot-TP-84M	
LCD Size		8.4"	
Max. Resolution		800 (W) x 600 (H)	
Brightness (cd/m ²)		350	
Contrast F	Ratio	600:1	
LCD Color		262K	
Pixel Pitch	n (H x V) (mm)	0.213 (H) x 0.213 (V)	
Viewing A	ngle (H-V)	130° / 150°	
Backlight	MTBF (hr)	50,000 (LED backlight)	
Touchscreen		4-wire resistive type touchscreen	
		Touch controller: Penmount DMC9000	
	Emergency Stop Button	For B contacts, two circuit outputs (forced disjunction	
		type)	
Switches	Deadman Switch	3-position switch (off-on-off), two circuit outputs	
	Mode Selector Switch	3-position (Auto, Manual, Teach) key switch	
	Video Input	VGA	
I/O	Touch Interface	RS-232	
	Power Source	12 V DC input	
OSD Control		Software OSD	
Construction Material		PC + ABS plastic front frame	
Front Panel Color		Black	
Weight (N)		3.3 kg	

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Robot-TP-84M

Dimensions (W x H x D) (mm)	321.67 x 204.00 x 81.41
Operating Temperature	0°C ~ 50°C
Storage Temperature	-25°C ~ 65°C
Humidity	<90% (no-condensing)
IP Level	IP 64 compliant (6-side)
Vibration	MIL-STD-810F 514.5C-1
Drop Survival	1 m (38 inches), six sides, compliant with IEC60068-2-32
Power Requirement	12V DC
Power Consumption	6.6 W
Cable Length	6 m

Table 1-2: System Specifications



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Unpacking



2.1 Unpacking

To unpack the Robot-TP-84M, follow the steps below:

The front side LCD screen has a protective plastic cover stuck to the screen. Only remove the plastic cover after the Robot-TP-84M has been properly installed. This ensures the screen is protected during the installation process.

- Step 1: Use box cutters, a knife or a sharp pair of scissors that seals the top side of the box.
- **Step 2:** Open the box.
- Step 3: Remove both polystyrene cover.
- **Step 4:** Lift the monitor out of the boxes.
- **Step 5:** Pull the plastic cover off the Robot-TP-84M.
- Step 6: Make sure all the components listed in the packing list are present.

2.2 Packing List

The Robot-TP-84M teach pendant is shipped with the following components:

Quantity	Item	Image
Standard		
1	Robot-TP-84M teach pendant	
2	Кеу	X
1	Touch pen	
1	Shoulder belt	
1	Utility CD	

If any of these items are missing or damaged, contact the distributor or sales representative immediately.

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Installation

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3.1 Anti-static Precautions



Failure to take ESD precautions during the maintenance of the Robot-TP-84M may result in permanent damage to the Robot-TP-84M and severe injury to the user.

Electrostatic discharge (ESD) can cause serious damage to electronic components, including the Robot-TP-84M. Dry climates are especially susceptible to ESD. It is therefore critical that whenever the Robot-TP-84M is accessed internally, or any other electrical component is handled, the following anti-static precautions are strictly adhered to.

- Wear an anti-static wristband: Wearing a simple anti-static wristband can help to prevent ESD from damaging the board.
- Self-grounding: Before handling the board touch any grounded conducting material. During the time the board is handled, frequently touch any conducting materials that are connected to the ground.
- Use an anti-static pad: When configuring the Robot-TP-84M, place it on an anti-static pad. This reduces the possibility of ESD damaging the Robot-TP-84M.
- Only handle the edges of the PCB: When handling the PCB, hold the PCB by the edges.

3.2 Installation Precautions

When installing the Robot-TP-84M, please follow the precautions listed below:

- Power turned off: When installing the Robot-TP-84M, make sure the power is off. Failing to turn off the power may cause severe injury to the body and/or damage to the system.
- Certified Engineers: Only certified engineers should install and modify onboard functionalities.



Anti-static Discharge: If a user open the rear panel of the Robot-TP-84M, to configure the jumpers or plug in added peripheral devices, ground themselves first and wear an anti-static wristband.

3.3 System Connection

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The Robot-TP-84M series has two models: Robot-TP-84M/K-ML and Robot-TP-84M/K. The only difference of these two models is that the Robot-TP-84M/K-ML has a 37-pin military connector while the Robot-TP-84M/K has multiple cables and connectors for connection. The following sections describe the system connection and connector pinouts of these two models.

3.3.1 Robot-TP-84M/K-ML Connection

The Robot-TP-84M/K-ML has a 6-meter cable with a 37-pin military connector to be connected to a robot controller.



Figure 3-1: Robot-TP-84M/K-ML with Cable

The pinout locations and pinouts of the 37-pin connector are described below.





Figure 3-2: 37-pin Military Connector Pinout Locations

PIN NO.	DESCRIPTION	PIN NO.	DESCRIPTION
1	Key SW Manual	20	RS-232 – SOUT
2	EMG2	21	
3	EMG1	22	RS-232 – RTS
4		23	
5	RS-232 - GND	24	
6		25	
7	RS-232 - chassis	26	GND
8		27	DDC – DAT
9	-(N)	28	DDC CLOCK
10		А	R (Red+)
11		В	GND (Red-)
12	+ (P)	С	G (Green+)
13	3 SW.2	D	GND (Green-)
14	3 SW.1	E	B (Blue+)
15	Key SW Teach	F	GND (Blue-)
16	+12V	G	VSYNC
17	GND	Н	HSYNC
18		J	Copper Shielding Mesh
19	RS-232 – SIN		

Table 3-1: 37-pin Military Connector Pinouts

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3.3.2 Robot-TP-84M/K Connection

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The Robot-TP-84M/K has following cables and connectors for connecting to a robot controller:

- OSD keypad connector (PS/2)
- Touch connector (DB-9 male)
- VGA connector (DB-15 male)
- Cables:
 - O Monitor power
 - O EMG
 - O Key switch
 - O 3-way switch
 - O LED



Figure 3-3: Robot-TP-84M/K with Cables

The pinout locations and pinouts of these connectors are described in the following sections.

3.3.2.1 OSD Keypad Connector



Figure 3-4: OSD Keypad Connector Pinout Locations

PIN NO.	DESCRIPTION
1	KB_DATA
2	
3	GND
4	PS/2 VCC_IN 5V
5	KB_CLK
6	



3.3.2.2 Touch Connector



Figure 3-5: Touch Connector Pinout Locations

PIN NO.	DESCRIPTION
1	
2	RS-232_RX
3	RS-232_TX
4	
5	GND

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6	
7	RS-232_RTS
8	
9	

Table 3-3: Touch Connector Pinouts

3.3.2.3 VGA Connector



Figure 3-6: VGA Connector Pinout Locations

PIN NO.	DESCRIPTION	PIN NO.	DESCRIPTION
1	RED	9	
2	GREEN	10	
3	BLUE	11	
4		12	DDC_DATA
5	GND	13	HSYNC
6	(Shield) RED	14	VSYNC
7	(Shield) GREEN	15	DDC_CLOCK
8			

Table 3-4: VGA Connector Pinouts

3.3.2.4 Cable Pinouts

	NO.	COLOR		DESCRIPTION		
Monitor	1	White		Vin-in (12V only)		
	2	Black		GND		
EMG	1 Red		EMG 1			
	2	Yellow		EMG 2		
Кеу	1	Black	Black 3 SW.2			
Switch	2	Brown		KEY SW-Teach		
	3	Orange		KEY SW-Manual		
3-Way	1	Green		3 SW.2		
Switch	2	Blue		3 SW.1		
LED	1	Purple		LED_Power (VCC 12~24V)		
	2	Gray		LED_Ready		
	3	White		LED_Auto		
	4	Pink		LED_Servo		
	5	Light green		LED_Enable		
	6	White/Black		LED_GND		

Table 3-5: Cable Pinouts

3.4 Carrying the System

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The package comes with a belt for the user to carry the Robot-TP-84M. To use the belt, follow the steps below.

Step 1: Locate the hooks on the four corners of the Robot-TP-84M (Figure 3-7).





- **Step 2:** Choose either two hooks to install the belt.
- Step 3: Carry the Robot-TP-84M as shown in Figure 3-8.



Figure 3-8: Carrying the Robot-TP-84M

3.5 Operation Mode Selection

The operation mode selector switch allows users to select the operation mode of the Robot-TP-84M teach pendant. The following three operation modes are available.

- Manual
- Auto
- Teach

The mode selector switch is a key switch. Please use the key come with the Robot-TP-84M to switch the operation mode.



Figure 3-9: Mode Selector Switch with Key

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3.6 Emergency Buttons

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The Robot-TP-84M teach pendant has a deadman switch and an emergency button, which are provided to stop the robot automatically and safely when the operator can no longer operate the robot correctly with the teach pendant in the manual mode.

3.6.1 Deadman Switch



Figure 3-10: Deadman Switch

The deadman switch is located on the rear panel. It is a 3-position switch which is able to react to the following three operating statuses:

- (1) OFF: When the switch is not being pressed or is being pressed lightly
- (2) ON: When the switch is being pressed with correct pressure
- (3) OFF: When the switch is being pressed too strongly

3.6.2 Emergency Stop Button



Figure 3-11: Emergency Stop Button

The emergency stop button is located on the front panel. Push the button can stop the robot operation immediately.

- **STOP:** Push the emergency stop button to stop operation.
- RESET:
 - O Pull the emergency stop button to reset or
 - O Turn the emergency stop button to rest



Pull to reset



Turn to reset

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Safety Precautions







The precautions outlined in this chapter should be strictly followed. Failure to follow these precautions may result in permanent damage to the Robot-TP-84M.

A.1 Safety Precautions

Please follow the safety precautions outlined in the sections that follow:

A.1.1 General Safety Precautions

Please ensure the following safety precautions are adhered to at all times.

- Follow the electrostatic precautions outlined below whenever the device is opened.
- Make sure the power is turned off whenever the Robot-TP-84M is being installed, moved or modified.
- If considerable amounts of dust, water, or fluids enter the device, turn off the power supply immediately, unplug the power cord, and contact the Robot-TP-84M vendor.
- DO NOT:
 - O Drop the device against a hard surface from a distance over 1 meter.
 - O Strike or exert excessive force onto the LCD panel.
 - O Touch any of the LCD panels with a sharp object
 - O In a site where the ambient temperature exceeds the rated temperature

A.1.2 Anti-static Precautions



Failure to take ESD precautions during the installation of the Robot-TP-84M may result in permanent damage to the Robot-TP-84M and severe injury to the user.

Electrostatic discharge (ESD) can cause serious damage to electronic components, including the Robot-TP-84M. Dry climates are especially susceptible to ESD. It is therefore critical that whenever the Robot-TP-84M is opened and any of the electrical components are handled, the following anti-static precautions are strictly adhered to.

- Wear an anti-static wristband: Wearing a simple anti-static wristband can help to prevent ESD from damaging any electrical component.
- Self-grounding: Before handling any electrical component, touch any grounded conducting material. During the time the electrical component is handled, frequently touch any conducting materials that are connected to the ground.
- Use an anti-static pad: When configuring or working with an electrical component, place it on an anti-static pad. This reduces the possibility of ESD damage.
- Only handle the edges of the electrical component: When handling the electrical component, hold the electrical component by its edges.

A.1.3 Product Disposal



Risk of explosion if battery is replaced by an incorrect type. Only certified engineers should replace the on-board battery.

Dispose of used batteries according to instructions and local regulations.

- Outside the European Union If you wish to dispose of used electrical and electronic products outside the European Union, please contact your local authority so as to comply with the correct disposal method.
- Within the European Union The device that produces less waste and is easier to recycle is classified as electronic device in terms of the European Directive 2012/19/EU (WEEE), and must not be disposed of as domestic garbage.



EU-wide legislation, as implemented in each Member State, requires that waste electrical and electronic products carrying the mark (left) must be disposed of separately from normal household waste. This includes monitors and electrical accessories, such as signal cables or power cords. When you need to dispose of your display products, please follow the

guidance of your local authority, or ask the shop where you purchased the product. The mark on electrical and electronic products only applies to the current European Union Member States.

Please follow the national guidelines for electrical and electronic product disposal.

A.2 Maintenance and Cleaning Precautions

When maintaining or cleaning the Robot-TP-84M, please follow the guidelines below.



For safety reasons, turn-off the power and unplug the monitor before cleaning.

A.2.1 Maintenance and Cleaning

Prior to cleaning any part or component of the Robot-TP-84M, please read the details below.

- To clean the LCD panel, gently wipe it with a piece of soft dry cloth or a slightly moistened cloth.
- The interior of the device does not require cleaning. Keep fluids away from the device interior.
- Be cautious of all small removable components when vacuuming the device.
- Never drop any objects or liquids through the openings of the device.
- Be cautious of any possible allergic reactions to solvents or chemicals used when cleaning the device.
- Avoid eating, drinking and smoking within vicinity of the device.

A.2.2 Cleaning Tools

Some components in the Robot-TP-84M may only be cleaned using a product specifically designed for the purpose. In such case, the product will be explicitly mentioned in the cleaning tips. Below is a list of items to use when cleaning the Robot-TP-84M.

- Cloth Although paper towels or tissues can be used, a soft, clean piece of cloth is recommended when cleaning the device.
- Water or rubbing alcohol A cloth moistened with water or rubbing alcohol can be used to clean the device.
- Using solvents The use of solvents is not recommended when cleaning the device as they may damage the plastic parts.

- Vacuum cleaner Using a vacuum specifically designed for computers is one of the best methods of cleaning the device. Dust and dirt can restrict the airflow in the device and cause its circuitry to corrode.
- Cotton swabs Cotton swaps moistened with rubbing alcohol or water are excellent tools for wiping hard to reach areas.
- Foam swabs Whenever possible, it is best to use lint free swabs such as foam swabs for cleaning.





Hazardous Materials Disclosure

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The details provided in this appendix are to ensure that the product is compliant with the Peoples Republic of China (China) RoHS standards. The table below acknowledges the presences of small quantities of certain materials in the product, and is applicable to China RoHS only.

A label will be placed on each product to indicate the estimated "Environmentally Friendly Use Period" (EFUP). This is an estimate of the number of years that these substances would "not leak out or undergo abrupt change." This product may contain replaceable sub-assemblies/components which have a shorter EFUP such as batteries and lamps. These components will be separately marked.

Please refer to the following table.

Part Name	Toxic or Hazardous Substances and Elements						
	Lead	Mercury	Cadmium	Hexavalent	Polybrominated	Polybrominated	
	(Pb)	(Hg)	(Cd)	Chromium	Biphenyls	Diphenyl Ethers	
				(CR(VI))	(PBB)	(PBDE)	
Housing	0	0	0	0	0	0	
Display	0	0	0	0	0	0	
Printed Circuit	0	0	0	0	0	0	
Board							
Metal Fasteners	0	0	0	0	0	0	
Cable Assembly	0	0	0	0	0	0	
Fan Assembly	0	0	0	0	0	0	
Power Supply	0	0	0	0	0	0	
Assemblies							
Battery	0	0	0	0	0	0	
O: This toxic or hazardous substance is contained in all of the homogeneous materials for the part is below the limit							
requirement in SJ/T11363-2006 (now replaced by GB/T 26572-2011).							

X: This toxic or hazardous substance is contained in at least one of the homogeneous materials for this part is above the limit requirement in SJ/T11363-2006 (now replaced by GB/T 26572-2011).

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此附件旨在确保本产品符合中国 RoHS 标准。以下表格标示此产品中某有毒物质的含量符 合中国 RoHS 标准规定的限量要求。

本产品上会附有"环境友好使用期限"的标签,此期限是估算这些物质"不会有泄漏或突变"的 年限。本产品可能包含有较短的环境友好使用期限的可替换元件,像是电池或灯管,这些元 件将会单独标示出来。

部件名称	有毒有害物质或元素					
	铅	汞	镉	六价铬	多溴联苯	多溴二苯
	(Pb)	(Hg)	(Cd)	(CR(VI))	(PBB)	醚
						(PBDE)
壳体	0	0	0	0	0	0
显示	0	0	0	0	0	0
印刷电路板	0	0	0	0	0	0
金属螺帽	0	0	0	0	0	0
电缆组装	0	0	0	0	0	0
风扇组装	0	0	0	0	0	0
电力供应组装	0	0	0	0	0	0
电池	0	0	0	0	0	0

O: 表示该有毒有害物质在该部件所有物质材料中的含量均在 SJ/T 11363-2006 (现由 GB/T 26572-2011 取代)标准规定的限量要求以下。

X: 表示该有毒有害物质至少在该部件的某一均质材料中的含量超出 SJ/T 11363-2006 (现由 GB/T 26572-2011 取代)标准规定的限量要求。