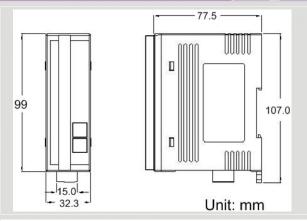
PWM module of DeviceNet Slave





CAN-2088D



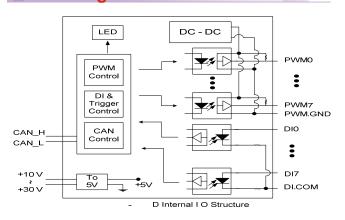
Dimensions

PWM (Pulse width modulation) is a powerful technique for controlling analog circuits. By using digital outputs, it can generate a waveform with variant duty cycle and frequency to control analog circuits. CAN-2088D, a CAN bus remote I/O modules with DeviceNet protocol, provides 8 PWM output channels and 8 digital inputs channels with high-speed counter function. It can be used to develop practical and economical analog control systems in the CANopen network.

Features

- Hardware-controlled PWM output.
- PWM output frequency: $0.2 \text{ Hz} \sim 500 \text{ kHz}$ with $0.1\% \sim 99.9\%$ duty cycle.
- PWM Output Modes: software trigger / hardware trigger.
- Trigger each PWM output individually or all PWM outputs synchronously.
- Support Burst output mode and Continue output mode.
- Provide 32-bit 500 kHz high-speed counter for each DI channel.
- Pass the validation of DeviceNet conformance test.
- Provide EDS file for DeviceNet master interface.

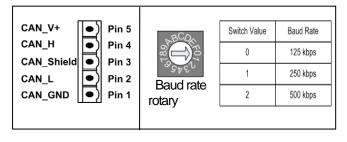
Block Diagram



I/O Pin & Wire Connection

Terminal No.			Pin Assignment	Output Type	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0
	[ت]	100	PO.0		Relay On	Relay Off
		02	PO.1		9	_ ^
		03	PO.2	Drive Relay	□ POX	□□ x □⊖ PO X
	٥	04	PO.3		⊕ PO.GND	PO.GND PO.GND
		05	PO.4	Resistance Load		
	ر م ا	06	PO.5		†	† x relleov
	<u></u>	07	PO.6		PO X	PO X
	[D	08	PO.7		÷ [20]]	÷ [50][[101015]
	[o	09	PO.GND	Input Type	ON State LED ON Readback as 1	OFF State LED OFF
	0 7	10	PO.GND		Relay On	Readback as 0 Relay Off
	50	11	DI.0	Relay Contact	+ DIX	+ DIX
	J 0	12	DI.1		Relay Close DI.GND	Refay Open DI.GND
		13	DI.2	TTL/CMOS Logic	Voltage > 10 V	Voltage < 4 V
	- O	14	DI.3		Logic Power C Logic Level Low DI X DI SND	Logic Power Logic Level Low DI X DI JOHN
		15	DI.4			[-0]]
	, o (16	DI.5	NPN Output	Open Collector On	Open Collector Off
	[o]	17	DI.6		□ DI X DI.GND	OFF ☐ ☐ ☐ DI X ☐ ☐ DI.GND
	\ 0	18	DI.7	PNP Output	Open Collector On	Open Collector Off
	2	19	DI.GND		ON ₹ DIX	OFFET → □ □ □ DI X
	_ D	20	DI.GND		DI.GND	DI.GND DI.GND

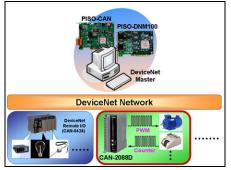
CAN Pin & Baud Rate Rotary

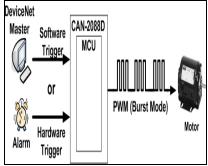


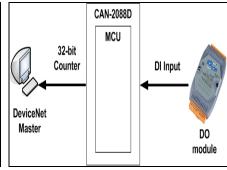
Hardware Specifications

CAN Interface						
DeviceNet Specification	Volume I, Release 2.0 & Volume II, Release 2.0, Errata 5					
DeviceNet subscribe	Group 2 Only Server					
Connection supported	1 connection for Explicit Messaging 1 connection for Polled I/O 1 connection for Bit-Strobe I/O					
Node ID	0~63 selected by rotary switch					
Baud Rate (bps)	125 kbps, 250 kbps, 500 kbps					
Heartbeat message	Yes					
Shutdown message	Yes					
Terminator Resistor	Switch for 120 Ω terminator resistor					
PWM Interface	PWM Interface					
Channels	8 (Source)					
Frequency Range	$0.2 \text{ Hz} \sim 500 \text{ kHz}$ (non-continuous, the min. units of the high/low level signal is 1 us).					
PWM Mode	Continue mode, Burst mode, Hardware trigger mode, Software trigger mode					
ESD Protection	4 kV Contact for each channel					
DI Interface						
Channels	8 (Sink)					
Counter Frequency	32-bit, 500 kHz Max.					
LED						
Round LED	PWR LED, NET LED, MOD LED					
I/O LED	8 LEDs as PWM, 8 LEDs as Digital Input, and 1 LED as terminal resister indicator					
Power						
Input range	Unregulated $+10 \sim +30 \text{ V}_{DC}$					
Power Consumption	3.5 W					
Mechanism						
Installation	DIN-Rail					
Dimensions	32.3 mm x 99 mm x 77.5 mm (W x L x H)					
Environment						
Operating Temp.	-25 ~ +75 °C					
Storage Temp.	-30 ~ +80 °C					
Humidity	10 ~ 90% RH, non-condensing					

Application







Ordering Information Art.-Nr. 125296

CAN-2088D

DeviceNet module of 8-channel PWM and 8-channel DI with high-speed counters.